

Address :3611, Hagun-ri, Yangchon-eup, Gimpo-si, Gyeonggi-do , South Korea (10048) Company Id No : 110111-243147 Tax & VAT Id No : 105-86-35114

Hot Issue

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Designated by Radio Research Institute



On November 29, 2017, I received the qualification from the National Institute of Radiological Research as **an Electromagnetic Compatibility Testing Laboratory.**

Based on this, ICR is providing **KC test** certification registration.



Designated by Radio Research Institute



Electromagnetic compatibility (03.011) _Designation number: KR0165

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% [Notification on Conformity Assessment of Broadcasting and Communication Equipment, etc.] Some revisions



1. Amendment of conformity identification marking method for broadcasting communication equipment

 In order to prevent confusion and inconvenience between businesses and consumers under the reorganization of government Used as a permanent identification label "R" that is not affected by changes in the name of the department in charge
How to display identification code

B	-	с	R	м	ſ	A	в	С	ſ	x	х	х	х	х	х	x	x	x	х	х	х	x	x
0		2	3	٩			5			6													
방송통신 기기식별		기 정	본인 보식	때 이었		신 정!	청 보식	자 별							제	품·	식법	별					

(New revision of existing broadcasting communication equipment identification code MSIP \rightarrow R) 2. Amendment of Applicable Laws for Registration of Designated Laboratory Conformity

(a) mobile means Reclassification of power transmission equipment

4. Household electric appliances		1) Electric motor bicycle			
and Electric motor current:		2) Electric motor board			
Household electrical	Power tools for moving means	3) Electric motor wheelchair			
electric heating devices and		4) Electric motor scooter			
Other electrical equipment		5) Other similar devices			

(b) Incorporate fire fighting equipment into the conformity assessment target device

	1) short circuit alarm	10) Hydraulic opening and closing device for starting			
	2) Gas leakage alarm	11) Commercial kitchen automatic fire extinguisher			
	3) Receiver	12) Automobile pressure, overpressure adjustable Tampere			
	4) repeater	13) Automatic closing device			
16. Fire fighting equipment	5) sensor	14) Cabinet Type Isfing Cooler Facility			
	6) Residential kitchen automatic fire extinguisher	15) Flap damper			
	7) Cabinet type automatic fire extinguisher	16) Guide light			
	8) Gas, powder automatic fire extinguisher	17) Emergency light			
	9) Solid aerosol automatic fire extinguisher 출저:http://www.rra	18) Other fire fighting equipment go.kr(국립전파연구원 고시 제2017-143			

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ICR Polska MD Scope Expansion



The Machinery Directive's task is to introduce rules about the sale of machines within the EU and to preserve the safety of consumers and workers.

If compliance is not met, it may prohibit placing them on the market or even order to withdrawal the machines that have already been placed on the market.

According to this rules, ICR Polska steadily expands **The Machinery Directive Scope**.

Additionally, **Mobile elevating work platforms** and **Vehicle Lifts** will be added to the scope in 2018.

ICR Polska MD Scope Expansion



Vehicle Lifts

Vehicle Lifts should be compliant with EN 1493:2010. It provides the safety requirements and solutions needed for possible hazards (e.g. mechanical hazards, electrical hazards, operating hazards, overloading hazards etc.).

Mobile elevating work platforms

Mobile elevating work platforms should be compliant with EN 280:2013. Because people ride on the work platforms, it shall be installed the safe guard and designed the work platforms to consider hazards about not only basic hazards, but also falling, slipping.







Changes of Multi–site certification criteria and certification activity branch control criteria

IAF MD1 will be published by combining MD19 and MD1

MD1 will be published in the first half of 2018. In the case of initial and recertification audit, 'multi-site which cannot be sampled', every site shall be audited. In the case of surveillance audit 30% of every site shall be audited.

■ The control criteria for certification activity branch will be tightened.

New IAF MD will be established, and risk assessment will be obliged. The contracted information for the branch shall be shared with the located national accreditation body.

K–OHSMS 18001 certification

KAB occupational health and safety management system certification

- Established: April 2002
- Certification standard: K-OHSMS 18001
- Number of certification body: 24
- Issued certificate: 2,311(Construction 50%,

Machinery, Electricity, Other transportation equipment 10% each)

K–OHSMS 18001 certification

ISO standard development status

The development of FDIS 45001 is finished in 20th October 2017, and it will be published in March 2018.

ISO 17021-10(Competence requirements for auditing and certification of occupational health and safety management systems) will be published in the second half of 2018(November~ December).

K–OHSMS 18001 certification

Migration instruction from OHSAS 18001 to ISO

45001

- Document type: IAF MD
- Publication schedule: January ~ Feburary 2018
- Contents

- Certification body: Gap analysis, Migration plan development

- Accreditation Body: Accreditation assessor training, Migration program development.

※ If 1M/D off-site assessment is positive, the migration would be acceptable. However, if the off-site assessment is negative, office or witness audit may required.

- Certification body: Human resource training, Migration plan development, Migration audit M/D X Migration audit standard: OHSAS 18001 and equal standard

Issue of a test report of KOLAS as to the railway goods



The ICR is recognized as an internationally accredited testing agency by the government(KOLAS, Korea Laboratory Accreditation Scheme) and provides product testing services with specialized skills and advanced testing equipment.

Recently, By expanding the test standards for railway equipment, it is possible to perform ' type approval ' work concerning railway equipment under the Railway Safety Act

What is 'type approval'?

Tests to verify safety and quality in relation to railway vehicle/equipment, whether the first built railway vehicle/equipment in accordance with the Railway Safety Act complies with the prescribed railway technical standards.



The status of KOLAS–related accreditation

Test method	Standard designation	Test method	Standard designation	
KS C IEC 62236- 1:2006	Railway applications – Electromagnetic compatibility – Part 1 : General	IEC 61373:2010	Railway applications – Rolling stock equipment – Shock and vibration tests	
KS C IEC 62236- 2:2006	Railway applications – Electromagnetic compatibility – Part 2: Emission of the whole railway system to the outside world	IEC 62498-3:2010	Railway applications – Environmental conditions for equipment – Part 3: Equipment for signalling and	
	Railway applications – Electromagnetic		telecommunications	
KS C IEC 62236-3- 1:2006	compatibility – Part 3- 1: Rolling stock – Train and complete vehicle	EN 50155:2007	Railway applications – Electronic equipment used on rolling stock	
KS C IEC 62236-3- 2:2006	Railway applications – Electromagnetic compatibility – Part 3- 2: Rolling stock - Apparatus	EN 61373:2010	Railway applications – Rolling stock equipment – Shock and vibration tests	
	Railway applications – Electromagnetic compatibility – Part 4:	KS C IEC 60571:2002	Railway applications – Electronic equipment used on rolling stock	
KS C IEC 62236- 4:2006	Emission and immunity of the signalling and telecommunications	KS C IEC 61373:2002	Railway applications – Rolling stock equipment – Shock and vibration tests	
KS C IEC 62236- 5:2006	Railway applications – Electromagnetic compatibility – Part 5: Emission and immunity of fixed	KS C 7620:2003	Railway car luminaries for fluorescent lamps	
	power supply installations and apparatus	KS R 9144:2014	Test methods for vibration of parts of railway rolling stock	
IEC 60571:2012	Railway applications – Electronic equipment used on rolling stock	KS R 9146:2002	Railway Rolling stock parts – Test methods for shock	

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The status of KOLAS–related accreditation

Test method	Standard designation		Test method	Standard designation
KS R 9156:2002	General rules for tests of electronic equipment used on railwayrolling stock Parts for railway signal – Vibration test methods		KS R 9213:2007	Railway rolling stock – High and low temperature test methods of parts
			KRS CS 0003-13:2013	Railway Rolling Stock- Test methods : Train signaling and
KS R 9186:1996				telecommunications
	Parts For Railway Signaling Waterproof Test Methods		KRS SG 0014- 16(R):2016	Power Supply for Signal Device
KS R 9189:2003			KRS SG 0015- 14(R):2014	Electronic Interlocking Device
KC D 0101.100C	High and Low temperature testing			
K2 K 9191:1990	methods for parts of railway signal			The Data Transmission
KS R 9192:1996	Change Of Temperature Testing Method For Parts of Railway Signaling		KRS CM 0026-16:2016	Train and Wayside(On- board Equipment)-Test methods
	Insulation Resistance			
KS R 9193:1996	And Withstand Voltage Testing Methods Of Parts For Railway Signaling		KRS SG 0033- 14(R):2014	Insulated Audio Frequency Track Circuit
	Test Methods For Insulation Resistance			
KS R 9197:1996	And Withstand Voltage Of Railway Rolling Stock		KRS SG 0036- 16(R):2016	Track Circuit Function Monitoring Device (TLDS)

The status of KOLAS–related accreditation



Test method	Standard designation	Test method	Standard designation
KRS SG 0038- 16(R):2016	Non-insulated Audio Frequency Track Circuit	KRS SG 0059- 14(R):2014	Automatic Train Stop Wayside Transmitter
KRS SG 0051- 14(R):2014	Railroad Crossing Control Unit(Plug in Type)	KRS SG 0067- 14(R):2014	Track-side subsystem- Test methods : Equipments for Signalling
KRS SG 0054- 14(R):2014	Single Track Automatic Block Control Device	KRCS C027 03:2011	Signal Floating Rectifier
KRS SG 0055- 14(R):2014	Double Track Automatic Block Control Device	KRCS C229 03:2016	Electronic Interlocking System

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Autonomous vehicle system configuration, element technology and development stage

According to the World Health Organization (WHO), millions of people are injured every day in the world and more than 3,500 people die from traffic accidents. The annual number of traffic accidents is 1.3 million, and if the increase is large, it is estimated that the number of traffic accident deaths in 2020 will reach 1.9 million a year. Also, according to the statistics of Korea's Road Traffic Corporation in 2015, more than 95% of all traffic accidents are caused by driver's carelessness.

Therefore, in order to minimize driver 's negligence and to reduce the loss of life caused by traffic accidents, advanced nations in the automotive industry have been supporting the development of autonomous vehicle technology by putting a lot of budget from early 90' s. The function of autonomous vehicle is largely composed of recognition, judgment and control.

[Source] Autonomous vehicle system configuration, element technology and development stage [Writer] MOT Consultant



Autonomous vehicle system configuration, element technology and development stage

Autonomous config	vehicle system guration	Element technology	ICT and OEM role expected			
	Path navigation	Precision mapping and positioning (High-altitude maps and high-precision GPS devices)	Lack of technical standards and open systems			
External driving environment recognition	Fixed entity recognition (Lanes, tunnels, etc.)	V2X communication (Vehicle to infra / Vehicle) (Adjacent vehicle and infrastructure communication)	-> We look at the trend of standardization of technology rather than proprietary			
	Variable - Moving object recognition (vehicles, pedestrians, traffic lights, etc.)	ADAS Sensor (Lidar Sterep, Camera, Rader etc)	relations with various companies			
Judgment and Driving	Situation determination and strategy establishment (car change, intervention, etc.)	Learning type judgment and control system (Autonomous driving record based algorithm)	Gain technology leadership with existing OEM realm And Investment Area for Retention			
Strategy	Driving trajectory generation (trajectory, speed, etc	Sensor based driving situation recognition system (Sensor based operation)	differentiation through independent investment -> Prior to the full-			
Vehicle control	Vehicle control (Steering, acceleration, deceleration, etc.)	Integrated Vehicle Control Solutions (Existing ADAS-based vehicle control system)	driving car and utilize demonstration materials			

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Development stage a Autonomous driving (SAE standard)



The Road Traffic Safety Administration and the Automotive Engineering Society (SAE) of the United States present the level of autonomous driving technology step by step.

Of these, SAE standards are the most common. SAE International's (On-Road Automated Vehicle Standards Committee), a global association of more than 128,000 engineers and related technical experts engaged in the aerospace, automotive and commercial vehicle industries in 2014, L5) proposed an automation level.

[Source] Autonomous vehicle system configuration, element technology and development stage [Writer] MOT Consultant

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Development stage a Autonomous driving (SAE standard)



Automati on stage	Characteris tic	Contents					
A person monitors the driving environment							
Level 0	Non- automatic	A step in which the driver entirely controls all operations and promotes all dynamic driving					
Level 1	Driver assistance	Where in the vehicle is run by a steering assist system or an acceleration / deceleration support system, but the person performs all the functions for the dynamic running of the vehicle					
Level 2	Partial automation	Although the car is operated by the steering assist system or the acceleration / deceleration support system, the driving environment is monitored by the person and the responsibility for safe driving is also borne by the driver					
A	utonomous dri	iving system monitors driving environment					
Level 3	Conditional automation	The system controls all aspects of the driving operation, but if the system asks the driver to intervene, the driver must properly control the vehicle and the responsibility lies with the driver.					
Level 4	Advanced automation	The system is carried out both in the core control of the driving, in the driving environment monitoring, and in the emergency, but the system is not always controlled at all times.					
Level 5	Fully automated	The system is in charge of all road conditions and environments.					



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